L Number	Hits	Search Text	D8	Time stamp
-	2	"20040010386"	USPAT;	2004/09/30 10:51
			US-PGPUB;	•
			EPO; JPO;	
			DERWENT;	
			IBM_TD8	
_	2	6683774.pn.	USPAT;	2004/08/27 11:05
	•	, COO 377 11pm	US-PGPUB;	
			EPO; JPO;	
			DERWENT;	
			IBM_TDB	,
	25652	rotational and angle and detection	USPAT;	2004/08/27 11:05
-	35652	rotational and angle and detection	US-PGPUB;	2007/00/27 11:03
				·
			EPO; JPO;	
		·	DERWENT;	
			IBM_TDB	2004/00/27 44.05
-	702	(rotational and angle and detection) and resolver	USPAT;	2004/08/27 11:05
			US-PGPUB;	
			EPO; JPO;	
			DERWENT;	
			IBM_TDB	
-	2857	(rotational and angle and detection) and offset and gain	USPAT;	2004/08/27 11:05
			US-PGPUB;	
			EPO; JPO;	
			DERWENT;	
			IBM_TDB	
-	133	((rotational and angle and detection) and resolver) and	USPAT;	2004/08/27 16:42
		((rotational and angle and detection) and offset and gain)	US-PGPUB;	, ,
		((, oaddonar and angre and accessor) and angre and	EPO; JPO;	
			DERWENT;	
			IBM_TDB	l
l _	4	(rotational near angle near detection) and offset and gain	USPAT;	2004/08/27 12:06
-	7	and maximum and minimum	US-PGPUB;	200 1,00,21
		and maximum and minimum	EPO; JPO;	
			DERWENT;	
1			IBM_TDB	
	350	resolver and offset and gain and maximum and minimum	USPAT;	2004/09/17 12:49
-	330	TESOIVER and Offset and gain and maximum and minimum	US-PGPUB;	200 1/05/17 12:15
			EPO; JPO;	
1				
			DERWENT;	
	_	(and the same and	IBM_TDB	2004/09/27 12:56
-	1	(correcting near resolver near output).ti.	USPAT;	2004/08/27 12:56
			US-PGPUB;	
			EPO; JPO;	
			DERWENT;	
			IBM_TDB	2004/00/27 42 55
-	1	correcting near resolver near output	USPAT;	2004/08/27 12:56
			US-PGPUB;	
		•	EPO; JPO;	
		•	DERWENT;	
			IBM_TDB	
-	686	correcting and resolver and output	USPAT;	2004/08/27 12:56
		`	US-PGPUB;	
			EPO; JPO;	
			DERWENT;]
			IBM_TDB	•
-	175	(correcting and resolver and output) and offset and gain	USPAT;	2004/08/27 14:16
		` · · · · · · · · · · · · · · · · · ·	US-PGPUB;	
			EPO; JPO;	
1			DERWENT;	1
			IBM_TDB	1
L	L	<u></u>	· · · · · · · · · · · · · · · · · · ·	

3934 rotational same angle same detection USPAT; US-RGPUB; EPO; JRO; DERWENT; IBM_TDB USPAT; US-RGPUB; E					
FPO_IPO_DERWENT; IBM_TDB USPAT; USPACPUB; PO_IPO_IPO_DERWENT; IBM_TDB USPAT; USPAT; USPACPUB; PO_IPO_IPO_DERWENT; IBM_TDB USPAT; USPACPUB; PO_IPO_DERWENT; IBM_TDB USPAT; USPAT; USPACPUB; PO_IPO_DERWENT; IBM_TDB USPACPUB; PO_IPO_DERWENT; PO_IPO_DERWENT; PO_IPO_DERWENT; PO_IPO_DERWENT; PO_IPO_DERWENT; PO_IPO_DERWENT; PO_IPO_DERWENT; PO_IPO_DERWENT; PO_IPO_DERWENT; PO_IPO_	-	3934	rotational same angle same detection	USPAT;	2004/08/27 14:17
Crotational same angle same detection and maximum and Crotational same angle same detection Crotational same angle same detection and maximum and Crotational same angle same detection					
326 (rotational same angle same detection) and maximum and minimum and average ((rotational same angle same detection) and maximum and minimum and average) and offset and gain (197, 190, 190, 190, 190, 190, 190, 190, 190				EPO; JPO;	
326 (rotational same angle same detection) and maximum and minimum and average ((rotational same angle same detection) and maximum and minimum and average) and offset and gain (197, 190, 190, 190, 190, 190, 190, 190, 190				DERWENT;	
326 (rotational same angle same detection) and maximum and minimum and average ((rotational same angle same detection) and maximum and minimum and average) and offset and gain ((rotational same angle same detection) and maximum and minimum and average) ((rotational same angle same detection) and maximum and minimum and average and sine and cosine (rotational same angle same detection) and maximum and minimum and average (rotational same angle same detection) and maximum and minimum and average (rotational same angle same detection) and maximum and minimum and average (rotational same angle same detection) and maximum and minimum and average (rotational same angle same detection) and maximum and minimum and average (rotational same angle same detection) and maximum and minimum and average (rotational same angle same detection) and maximum and minimum and average (rotational same angle same detection) and maximum and minimum and average (rotational same angle same detection) and maximum and minimum and average (rotational same angle same detection) and maximum and minimum and average (rotational same angle same detection) and maximum and minimum and average (rotational same angle same detection) and maximum and minimum and average (rotational same angle same detection) and maximum and minimum and average (rotational same angle same detection) and maximum and minimum and average (rotational same angle same detection) and maximum and minimum and average (rotational same angle same detection) and maximum and minimum and average (rotational same angle same detection) and maximum and average (rotational same angle same detection) and maximum and average (rotational same angle same detection) and maximum and average (rotational same angle same detection) and maximum and average (rotational same angle same detection) and maximum and average (rotational same angle same detection) and maximum and average (rotational same angle same detection) and maximum and average		į .			
Minimum and average US-PGPUB; EPO; JPO; DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; JPO; JPO; JPO; JPO; JPO; JPO; JPO; J		326	(rotational same angle same detection) and maximum and		2004/08/27 14:34
Crotational same angle same detection and maximum and minimum and average) and offset and gain Crotational same angle same detection Crotational same angle same angle same detection Crotational same angle same angle same detection Crotational same angle same detection Crotational same angle same angle same detection Crotational same angle same angle same detection Crotational same angle same angle same detection Crotational	1 -	320			200 1,00,27
DERWENT; IBM, TDB USPAT; USPGPUB; EPO; JPO; DERWENT; U	İ		i minimum and average		
Circtational same angle same detection) and maximum and suspar; US-PGPUB; EPO; JPO; JPO; JPO; JPO; JPO; JPO; JPO; J		j			
Circlational same angle same detection) and maximum and minimum and average and offset and gain USPAT; USP-GPUB; EPO; IPO; DERWENT; IBM, TDB USP-GPUB; EPO; IPO; DERWENT; ISM, TDB USP-GPU	1				
Minimum and average and offset and gain US-PGPUB; EPO; JPO; DERWENT; IBM_TDB USPAT; USPGPUB; EPO; JPO; USPAT;	+	1			
2 6097183.pn. EPO; JPO; DERWENT; IBM_TDB USPAT; US-PCPUB; EPO; JPO; JPO; JPO; JPO; JPO; JPO; JPO; J	-	61	((rotational same angle same detection) and maximum and		2004/08/27 15:21
DERWENT; IBM_TDB			minimum and average) and offset and gain		
2 6097183.pn. IBM_TDB USPAT; US-PGPUB; EPC; JPC; DERWENT; IBM_TDB USPAT; US-PGPUB; EPC; JPC; JPC; DERWENT; IBM_TDB USPAT; US-PGPUB; EPC; JPC; JPC; JPC; JPC; JPC; JPC; JPC; J	1	1		EPO; JPO;	
SPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; ISM_TDB USPAT; US-PGPUB; EPO;				DERWENT;	•
SPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; ISM_TDB USPAT; US-PGPUB; EPO;	1				
US-PGPUB; EPO; JPO; DERWENT; IBM_TDB US-PGPUB; EPO; JPO; DERWENT; ISM_TDB US-PGPUB; EPO; JPO; DERWENT; US-PGPUB; EPO; JPO;	1_	2	6097183 nn		2004/08/27 14:22
Crotational same angle same detection) and maximum and minimum and average and sine and cosine	1		1 0037 103.pm.		
Crotational same angle same detection Crotational same angle same and cosine Crotational same angle same and cosine Crotational same and cosine Cr					
33 (rotational same angle same detection) and maximum and minimum and average and sine and cosine IBM_TDB USPAT; USPGPUB; EPO; JPO; DERWENT; IBM_TDB USPAT; USPAT; USPGPUB; EPO; JPO; DERWENT; IBM_TDB USPAT; USPGPUB; EPO; JPO; DERWENT;					· I
-	1				
Minimum and average and sine and cosine US-PGPUB; EPO; JPO; DERWENT; IBM_TDB 2004/08/27 14:47 US-PGPUB; EPO; JPO; DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; ISPAT; US-P	1	j	<u> </u>		2004/00/07 44 57
FPO; JPO; DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; ISM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; ISM	-	33			2004/08/27 14:37
- 338 (resolver and average) nd offset and gain - 338 (resolver and average) and offset and gain - 34 (73/862.331.ccls. and maximum and minimum and average) - 34 (73/862.331.ccls. and maximum and minimum and average) - 34 (73/862.331.ccls. and maximum and minimum and average) - 34 (73/862.331.ccls. and maximum and minimum and average) - 34 (73/862.331.ccls. and maximum and minimum and average) - 34 (73/862.331.ccls. and maximum and minimum and average) - 34 (73/862.331.ccls. and maximum and minimum and average) - 34 (73/862.331.ccls. and maximum and minimum and average) - 34 (73/862.331.ccls. and maximum and minimum and average) - 35 (2004/08/27 14:48) - 36 (73/862.331.ccls. and maximum and minimum and average) - 37/862.331.ccls. and maximum and minimum and average - 37/862.331.ccls. and maximum and minimum and average - 37/862.331.ccls. and maximum and minimum and average - 37/862.326.ccls. and maximum and average - 3	1		minimum and average and sine and cosine		
Table					
SPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; US-PGPUB; EPO;				DERWENT;	
SPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; US-PGPUB; EPO;				IBM TOB	
- 4 73/862.326.ccls. and maximum and minimum and average	1_	5	73/862 331 ccls, and maximum and minimum and average		2004/08/27 14:47
- 2 73/862.326.ccls. and maximum and minimum and average	-		75/502.001. did filaminani did filaminani		,,
Taylor T		}			ļ
Taylor T			·		
- 2 5912638.pn. USPAT; USPGPUB; EPO; JPO; DERWENT; IBM_TDB USPAT; USPGPUB; EPO; JPO; DERWENT; USPGPUB; EPO; JPO; DERWENT; IBM_TDB USPAT; USPGPUB; EPO; JPO; DERWENT; USPGPUB; EPO; JPO; DERWE					
US-PGPUB; EPO; JPO; DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; US-PGPUB; EPO; DER		1	TO MOCD DOC and an advantage and extension and extension		2004/00/27 14:49
EPO; JPO; DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM	-	4	73/862.326.ccis. and maximum and minimum and average		2004/06/27 14:46
DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB USPAT					
- 2 5912638.pn. IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT;					
- 2 5912638.pn. USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; ISPAT; US-PGPUB; EPO;					
US-PGPUB; EPO; JPO; DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; EPO;					
US-PGPUB; EPO; JPO; DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; EPO;	-	2	5912638.pn.	USPAT;	2004/08/27 15:23
EPO; JPO; DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; US-PGPUB; EPO; JPO; DERWENT; US-PGPUB; EPO; JPO; DERWENT; US-PGPUB; EPO; JPO; DERWENT; EPO; JPO; DERWENT;				US-PGPUB;	
DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; EPO; JPO;	1	-	· ·		
- 2 4529922.pn. IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; US-PGPUB; EPO; JPO; DERW					
- 2 4529922.pn. USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; US-PGPUB; EPO; JPO; DERWENT; US-PGPUB; EPO; JPO; DERWENT;					
US-PGPUB; EPO; JPO; DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; US-PGPUB; EPO; JPO; DERWENT;	_	1	4529922 nn		2004/08/27 15·48
EPO; JPO; DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; US-PGPUB; EPO; JPO; DERWENT; US-PGPUB; EPO; JPO; DERWENT; US-PGPUB; EPO; JPO; DERWENT;	1	1 2	1 1323322.pm.		200 1, 30/27 23:10
DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; US-PGPUB; EPO; JPO; DERWENT; US-PGPUB; EPO; JPO; DERWENT;	1	1			
BM_TDB	1	1			
- 1470 resolver USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; US-PGPUB; EPO; JPO; DERWENT; US-PGPUB; EPO; JPO; DERWENT; US-PGPUB; EPO; JPO; DERWENT; DERWENT;	1				
US-PGPUB; EPO; JPO; DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; US-PGPUB; EPO; JPO; DERWENT; US-PGPUB; EPO; JPO; DERWENT;		1			2004/00/27 45:40
EPO; JPO; DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; US-PGPUB; EPO; JPO; DERWENT; DERWENT; DERWENT; DERWENT; DERWENT; DERWENT;	-	9055	resolver		2004/08/27 15:48
- 1470 resolver and average	1				
resolver and average resolver and average resolver and average resolver and average resolver and average) and offset and gain resolver and average) and offset and gain IBM_TDB USPAT; IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; DERWENT;	1	1			
- 1470 resolver and average USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; JPO; DEPO; JPO; DEPO; JPO; DEPO; JPO; DEPO; JPO; DERWENT;		1			
- 1470 resolver and average USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; JPO; DEPO; JPO; DEPO; JPO; DEPO; JPO; DEPO; JPO; DERWENT;	1			IBM_TDB	
US-PGPUB; EPO; JPO; DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; DEPO; JPO; DERWENT; DEPO; JPO; DERWENT; DERWENT; DERWENT;	-	1470	resolver and average		2004/08/27 15:48
EPO; JPO; DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; DERWENT; DERWENT; DERWENT; DERWENT;		1			
- 338 (resolver and average) and offset and gain USPAT; US-PGPUB; EPO; JPO; DERWENT;	1				
- 338 (resolver and average) and offset and gain USPAT; US-PGPUB; EPO; JPO; DERWENT;					
- 338 (resolver and average) and offset and gain USPAT; US-PGPUB; EPO; JPO; DERWENT;					ļ
US-PGPUB; EPO; JPO; DERWENT;	1		(manhan had manage) and offert and asin		2004/09/27 15:49
EPO; JPO; DERWENT;	-	338	(resolver and average) and offset and gain		2004/00/2/ 13:48
DERWENT;					
IBM_TDB	.1				
				IBM_TDB	<u></u>

-	302	((resolver and average) and offset and gain) and (maximum	USPAT;	2004/08/27 15:49
		or minimum)	US-PGPUB;	
			EPO; JPO;	
	İ		DERWENT;	
			IBM_TDB	
·-	223	((resolver and average) and offset and gain) and (maximum	USPAT;	2004/08/27 16:37
		and minimum)	US-PGPUB;	
1	ļ		EPO; JPO;	
			DERWENT;	
	,		IBM_TDB	
1 -	3	702/87.ccls. and resolver	USPAT;	2004/08/30 12:28
			US-PGPUB;	
			EPO; JPO;	
			DERWENT;	
			IBM_TDB	
	10	702/87.ccls. and rotational\$4	USPAT;	2004/08/30 12:38
		•	US-PGPUB;	
]	1		EPO; JPO;	
	1		DERWENT;	
			IBM_TDB	
1 -	0	702/87.ccls. and (rotational adj measuring adj device)	USPAT;	2004/08/30 12:39
		, , , , , , , , , , , , , , , , , , , ,	US-PGPUB;	
1	1		EPO; JPO;	
			DERWENT;	
		·	IBM_TDB	
l _	4	702/87.ccls. and rotational and angle and sensor	USPAT;	2004/08/30 12:50
ļ -	"	702/07.ccis. and roadonal and angle and sensor	US-PGPUB;	200 1, 00,00 00.00
			EPO; JPO;	
İ			DERWENT;	
1			IBM_TDB	
	9079	resolver or (rotational near angle near sensor) and offset	USPAT;	2004/08/30 12:53
-	9079	and gain	US-PGPUB;	200 1/00/00 22:00
		and yan	EPO; JPO;	
			DERWENT;	
	!		IBM_TDB	
	1762	(resolver or (rotational near angle near sensor) and offset	USPAT;	2004/08/30 12:53
1 -	1763		US-PGPUB;	200 1/00/30 12:33
]	and gain) and maximum and minimum	EPO; JPO;	
	1		DERWENT;	
		*	IBM_TDB	
Ì	330	((recent or or (retational near apple soor sensor) and officet	USPAT;	2004/08/30 12:57
-	329	((resolver or (rotational near angle near sensor) and offset	US-PGPUB;	2007/00/30 12.37
		and gain) and maximum and minimum) and sine and cosine	EPO; JPO;	
			DERWENT;	
			IBM_TDB	
		20020124662	USPAT;	2004/08/30 16:30
-	2	"20020124663"	US-PGPUB;	2007/00/30 10.30
Į			EPO; JPO;	
[DERWENT; IBM_TDB	
			_	2004/00/15 12:57
-	9107	resolver	USPAT;	2004/09/16 12:57
			US-PGPUB;	
Ì			EPO; JPO;	
			DERWENT;	
ļ		useshipp and offeet and cale	IBM_TDB	2004/00/16 12:57
1 -	664	resolver and offset and gain	USPAT;	2004/09/16 12:57
	ĺ		US-PGPUB;	'
1			EPO; JPO;	,
1			DERWENT;	
	L		IBM_TDB	L

-	45957	(resolver and offset and gain) and sine or cosine	USPAT;	2004/09/16 12:57
			US-PGPUB;	
			EPO; JPO;	
1			DERWENT;	1
			IBM_TDB	[
	249	(resolver and offset and gain) and sine	USPAT;	2004/09/16 12:58
•	243	(1650)Val and onset and gain) and sine	US-PGPUB;	200 1/03/10 12:30
			EPO; JPO;	,
			DERWENT;	8
Į.			IBM_TDB	
-	197	(resolver and offset and gain) and cosine	USPAT;	2004/09/16 12:58
i		,	US-PGPUB;	
		•	EPO; JPO;	
			DERWENT;	
			IBM_TDB	
	ا ۔	(harabless and again and offset	USPAT;	2004/09/17 12:54
-	5	(brushless near resolver) and gain and offset		2004/05/17 12.54
		,	US-PGPUB;	•
l			EPO; JPO;	
1			DERWENT;	
			IBM_TDB	
l -	334	(resolver and gain and offset) and correction	USPAT;	2004/09/17 12:53
	"	(, soon or anna gammana contra)	US-PGPUB;	·
			EPO; JPO;	
		•	DERWENT;	
	i			
			IBM_TDB	2004/00/47 42-55
-	550	(rotational near angle) and gain and offset	USPAT;	2004/09/17 12:55
}			US-PGPUB;	
		,	EPO; JPO;	
			DERWENT;	
	ŀ		IBM_TDB	
<u> </u>	321	((rotational near angle) and gain and offset) and correction	USPAT;	2004/09/17 14:35
1 -	J21	((Totalional flear angle) and gain and onsety and correspond	US-PGPUB;	200 1, 00, 21 2 1100
ì	1		EPO; JPO;	
1]		DERWENT;	
			IBM_TDB	2004/00/47 35.45
-	16	resolver and (differential near gain) and offset	USPAT;	2004/09/17 15:15
1			US-PGPUB;	
	}		EPO; JPO;	
	1		DERWENT;	
1	1		IBM_TDB	
1.	3	341/112.ccls. and differential and gain and offset	USPAT;	2004/09/17 16:21
1	1	O 12/222/00/01 WING WING OFFICE WING SUIT WING OFFICE	US-PGPUB;	
	}	•	EPO; JPO;	
1	l		DERWENT;	
1				
1	1	l	IBM_TDB	2004/00/47 46:44
-	31	341/112.ccls. and resolver	USPAT;	2004/09/17 16:41
1			US-PGPUB;	
1	1		EPO; JPO;	
1	1		DERWENT;	[
1			IBM_TDB	
1_	128	341/116.ccls. and resolver	USPAT;	2004/09/17 17:01
1	123	U IN A LUIGIDI MIM I CONTOI	US-PGPUB;	
	I		EPO; JPO;	
]
1	Į.		DERWENT;	
			IBM_TDB	2004/00/47 47 65
-	134	resolver and error and correction and average and	USPAT;	2004/09/17 17:02
1		differential and max and min	US-PGPUB;	
1			EPO; JPO;	
,			DERWENT;	
			IBM_TDB	
,	<u> </u>	1		

-	174	resolver and sine and cosine and offset and gain	USPAT;	2004/09/22 15:30
			US-PGPUB;	
			EPO; JPO;	
			DERWENT;	1
			IBM_TDB	
_	2	3974498.pn.	USPAT;	2004/09/30 10:52
		•	US-PGPUB;	
			EPO; JPO;	
			DERWENT;	-
1			IBM_TDB	•